

Course Review

Review of “Kernel Lectures”

- **Dense direct solvers**
- **Sparse direct solvers**
- Spectral methods
- N-body methods
- **Structured grids / iterative solvers**
- **Unstructured grids / iterative solvers**
- Monte Carlo (“MapReduce”)
- Combinatorial logic
- Graph traversal
- Graphical models
- Finite state machines
- Dynamic programming
- Backtrack and branch-and-bound

“Kernel Lecture” Topics

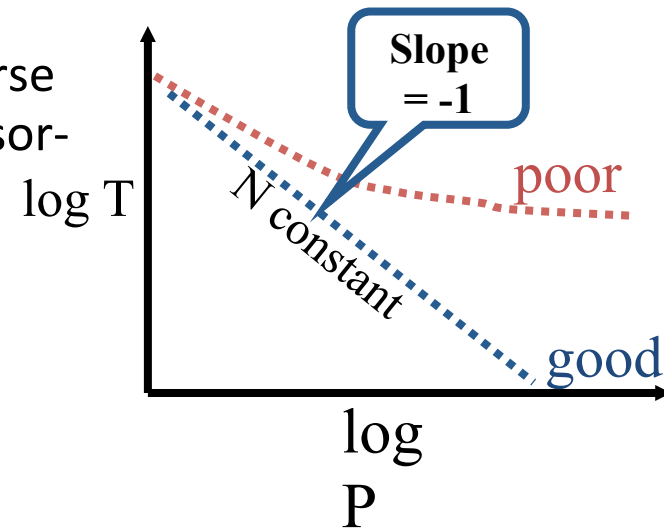
- Strong and weak scaling
- Speedup
- Efficiency
- The lack of unbounded strong scalability of almost all methods, due to Amdahl’s Law
- The lack of weak scalability of explicit methods, due to the CFL stability restriction
- Optimal complexity

Kernel topics, cont.

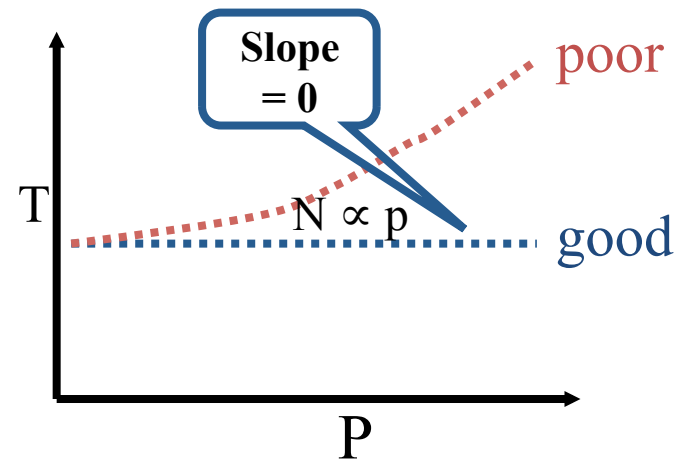
- Different kernels stress different parts of modern architecture
 - Computational capability (flops/second)
 - Memory bandwidth (bytes/second)
 - Memory latency (seconds)
 - Network bandwidth (bytes/second)
 - Network latency (seconds)

Colloquial definitions of scalability

- “Strong scaling”
 - execution time (T) decreases in inverse proportion to the number of processor-memory units (P)
 - *fixed size problem (N) overall*
 - often instead graphed as reciprocal, “speedup”



- “Weak scaling”
 - execution time remains constant, as problem size and processor number are increased in proportion
 - *fixed size problem per processor*
 - also known as “Gustafson scaling”



Four potential limiters on scalability

- Insufficient localized concurrency
- Load imbalance at synchronization points
- Interprocessor message latency
- Interprocessor message bandwidth

“horizontal aspects”

Four potential limiters on arithmetic performance

- Memory latency
 - failure to predict which data items are needed
- Memory bandwidth
 - failure to deliver data at consumption rate of processor
- Load/store instruction issue rate
 - failure of processor to issue enough loads/stores per cycle
- Floating point instruction issue rate
 - low percentage of floating point operations among all operations

“vertical aspects”

CS&E topics

- Well-posedness of a simulation
 - A *well-conditioned* problem, solved with a *stable* algorithm, can yield an *accurate* result
- Implications of the triple-finiteness of the computer
 - wordlength, number of words, number of flops
- Modeling hierarchy and triangle inequality
- Problem transformation and the quest for the reduced basis
 - “*Think. Then discretize.*” (V. Rokhlin)

CS&E topics

- The ***condition number*** is a scalar -- the multiplier by which, in the worst case, an error in the input can be multiplied to produce an error in the output
 - The input and output errors are measured in norms, which are also scalars
- For a linear system, $Ax=b$, the condition number can be expressed as a product of two operator norms: the norm of A and of its inverse
- For a symmetric linear system, specializing further, the norm of A is its largest eigenvalue of A and the norm of A^{-1} is the largest eigenvalue of A^{-1} , which is the smallest eigenvalue of A
- For the Laplacian on a uniform mesh, these eigenvalues can be calculated exactly

Nonlinear solver lectures

- Review of Newton's method for scalar nonlinear algebraic problems (classical "rootfinding")
 - Examples of quadratic convergence
 - Intuition about non-robustness
 - Globalization through linesearch and trust region
- Introduction of Newton's method for multivariate problems
 - Jacobian matrix inversion replaces the divided by $f'(x)$
- Nonlinear eq. solution reduces, in principle, to
 - Residual evaluation, Jacobian evaluation, linear equation solution, state-vector update
 - In practice, all aspects are modified